

Focal mechanisms in the southeastern South Island of Aotearoa New Zealand indicate scale-dependent partitioning of transpressional strain

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Abstract The classic Andersonian model of faulting is difficult to apply to plate boundaries with oblique motion, as displacement is accommodated across oblique-slip faults, or it is partitioned into distinct strike-slip and dip-slip faults. Here, we investigate how faults accommodate oblique plate motion by using the focal mechanism solutions of 126 M_L 1.3–4.3 earthquakes in the transpressional southeastern South Island of Aotearoa New Zealand. Focal mechanisms were assigned an *A-D* quality, and of the 91 *C* or better quality solutions, 57 are strike-slip. In addition, when incorporated into a stress inversion, these focal mechanisms indicate a strike-slip stress state with an WNW-trending maximum principal compressive stress. By contrast, constraints on active crustal-scale faulting from the New Zealand Community Fault Model indicate reverse faulting in this region. A high stress shape ratio can partly account for the coexistence of reverse and strike-slip faults. However, we also propose that the focal mechanisms are typically sampling slip on optimally-oriented small-scale faults in intact crust, while the larger magnitude reverse faulting reflects local stress rotations within pre-existing faults and shear zones in the southeastern South Island. Our study therefore demonstrates how inherited structures influence the scale and orientation of faults onto which transpressional strain is partitioned.

Non-technical summary When earthquakes occur, they release seismic waves. Since the motion within these waves has a predictable symmetry around the earthquake's causative fault, we can use seismic wave recordings to constrain the fault's orientation and slip sense. This information is represented using an earthquake 'focal mechanism.' In this study, we derived 126 focal mechanisms from small (M 1.3–4.3) earthquakes in the southeastern South Island of New Zealand, where the Australian and Pacific plates are moving through a combination of collision and horizontal lateral movement. However, the earthquake focal mechanisms we recorded generally indicate horizontal lateral movement. By contrast, large-scale faults in this region indicate convergence. From these observations, we suggest there is a scale dependence for how Australian-Pacific plate motion is being accommodated in the southeastern South Island, with lateral and convergence motions being accommodated in small and large earthquakes respectively.

1 Introduction

Our understanding of the relationship between fault orientations and stress states in the Earth's crust has a wide range of utilities for evaluating current and past crustal dynamics (Mercier et al., 1987; Hardebeck and Hauksson, 2001; Lanari et al., 2020), fluid flow (Barton and Zoback, 1992; Sibson, 1994; Ferrill et al., 2019), and seismic hazard (Morris et al., 1996; López, 2012; Yukutake et al., 2015; Williams et al., 2019). In isotropic crust undergoing plane strain, crustal stresses can be conveniently divided into 'Andersonian' normal, reverse, or strike-slip stress states, each of which has a predictable

set of optimally-oriented conjugate faults (Anderson, 1905; Lisle et al., 2006; Célérier, 2008; Fossen, 2020). However, these predictions cannot be easily applied to regions experiencing transpressional or transtensional strain. Instead, these regions accommodate plate motion across oblique-slip faults or by the partitioning of strain into its pure and simple shear components (e.g., Sanderson and Marchini, 1984; Lettis and Hanson, 1991; Teyssier et al., 1995; Jones and Tanner, 1995; Dewey et al., 1998; Tamas et al., 2021; Zhang et al., 2025).

Earthquake focal mechanisms are a particularly useful tool for evaluating how transpressional and transtensional strain is released, as they provide in-situ information about fault orientations and kinematics. Furthermore, assuming that the maximum resolved shear stress acting on the fault plane is paral-

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lel to fault slip, focal mechanisms can be used to derive and map the crust's principal stresses orientations and relative magnitudes (e.g., Michael, 1984; Vavryčuk, 2014; Heidbach et al., 2018; Martínez-Garzón et al., 2016). However, focal mechanisms and stress states can be challenging to interpret in regions where strain is partitioned, as this implies small-scale switching of the principal strain and stress axes (Jones and Tanner, 1995; Abercrombie et al., 2000; Sibson et al., 2012; Kim et al., 2023). This can be further complicated in regions where the crust contains pre-existing faults and fabrics that can reactivate as unfavorably oriented oblique-slip faults (Lanari et al., 2020; Tamas et al., 2021) or that can locally rotate the principal stress axes (e.g., Twiss and Unruh, 1998; Faulkner et al., 2006; Morley, 2010; Williams et al., 2019).

In this study, we evaluate how oblique plate motion is accommodated between the Australian and Pacific plates on the southeastern South Island of Aotearoa New Zealand. In doing so, we explore an apparent contradiction between previous studies from in and around this region, which indicate a strike-slip stress state (e.g., Townend et al., 2012; Warren-Smith et al., 2017a,b; Holbek et al., 2020), and the surface expression of its active faults, which is comprised of a dominant set of NE-striking reverse faults and subordinate NW-striking reverse faults (Barrell, 2016, 2019; Seebeck et al., 2024). To do this, we resolve a new set of focal mechanisms for the southeastern South Island from temporary seismic array data (Reyners et al., 2017; Williams et al., 2025b), and from which we propose a model for scale-dependent release of transpressional strain.

2 Southeastern South Island seismotectonic setting

Within the South Island of Aotearoa New Zealand, the Pacific and Australian plates are obliquely converging along an ENE-trending azimuth at 35-40 mm/yr (Fig. 1; DeMets et al., 2010). In the southern South Island, the majority (~70-90%) of this plate motion is accommodated to the west through dextral strike-slip on the Alpine Fault's southern section and convergence across the Puysegur Subduction Zone (Norris et al., 1990; Norris and Cooper, 2001; Barnes, 2009; Barth et al., 2014). Further east, is a ~100-200 km wide low strain rate region that extends from the eastern edge of the Southern Alps and Fiordland to the South Island's east coast, and which forms the basis of our study area (Fig. 1).

From considering borehole breakouts (Sibson et al., 2012), slickenside orientations on outcrop-scale fault networks (Holbek et al., 2020), and first motion focal mechanisms (Balfour et al., 2005; Townend et al., 2012; Warren-Smith et al., 2017a,b; Matsuno et al., 2022), the stress tensor across the South Island is characterized by a strike-slip stress state (vertical stress, σ_v , = the intermediate principal compressive stress, σ_2) with a sub-horizontal ESE-trending maximum principal stress (σ_1). There are, however, nuances to this suggestion. Firstly, the stress state within our southeastern South Island study area is poorly constrained as low seismic-

ity rates and the sparse coverage of the permanent GeoNet network (Eberhart-Phillips and Reyners, 2023; Warren-Smith et al., 2024) has made it challenging to obtain focal mechanisms from this region. More pertinently, while focal mechanisms indicate a strike-slip stress state, active fault maps and geodetic data indicate that deformation in the southeastern South Island is mainly accommodated on NE-striking reverse faults (Fig. 1a; e.g., Denys et al., 2016; Barrell, 2019, 2021; Seebeck et al., 2024). Because of these observations, the 2022 New Zealand National Seismic Hazard Model's (NZ NSHM 2022) distributed seismicity model considers both strike-slip and reverse mechanisms in this region (Thingbaijam et al., 2023).

In addition, the presence of the active NW-striking Waitaki and Waihemo reverse faults systems in north Otago/south Canterbury implies that σ_1 is locally rotated to a NE trend (Fig. 1a; Forsyth, 2002; Barrell et al., 2009; Upton et al., 2009; Gorman et al., 2013; Barrell, 2016, 2019; Seebeck et al., 2024). NE-oriented convergence around these faults is also supported by geodetic data (Denys et al., 2016; Haines and Wallace, 2020). NW-striking reverse faults are also mapped in south Otago and Southland (e.g., Tuapeka, Old Man, Clifton, and Hillfoot). Evidence of late Quaternary activity across these faults is equivocal (Fig. 1a; Hull and Stirling, 1992; Barrell, 2019), however, they have been active within southern New Zealand's current plate tectonic setting (i.e., since the late Miocene; Turnbull and Allibone, 2003; Cox and Sutherland, 2007; Barrell, 2021; Craw et al., 2022).

3 Methods

3.1 Southeastern South Island temporary seismic array deployments

We obtain focal mechanisms from earthquakes recorded by two temporary seismic deployments in the southeastern South Island, and which supplement the otherwise sparse (~100 km station spacing) permanent GeoNet network in this region. The 'Otago' network (henceforth referred to as 'OtagoNet') was deployed between March 2014-April 2015, and consisted of a 40 station portable broadband network between southern Canterbury and eastern Southland (Fig. 1b; Reyners et al., 2017; Eberhart-Phillips et al., 2018, 2022b). For the Southland Otago Seismic Array (SOSA), 19 short period sensors were deployed from October 2022-October 2023 between eastern Southland and the edge of Fiordland (Fig. 1b; Williams et al., 2025b). This deployment was also supplemented by an ongoing temporary network in Fiordland (Fiord22; Eberhart-Phillips et al., 2023). Detected events were located with Simul2023 (Thurber and Eberhart-Phillips, 1999; Eberhart-Phillips et al., 2024) using the nzwide 3-D velocity model (Eberhart-Phillips et al., 2022a). Further details about these deployments, and how events were located, can be found in Reyners et al. (2017), Eberhart-Phillips et al. (2022b), and Williams et al. (2025b).

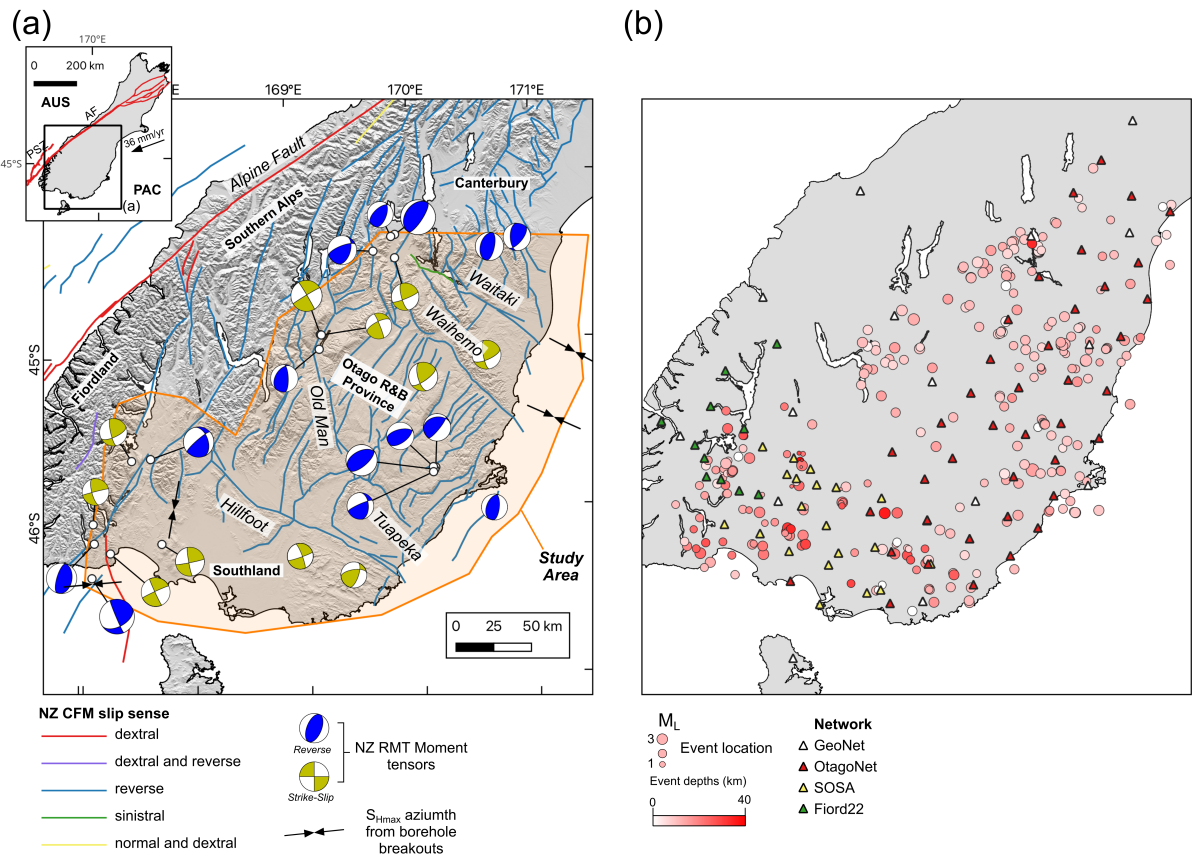


Figure 1 (a) Seismotectonic setting of the southeastern South Island of New Zealand as indicated by the distribution and kinematics of faults in the New Zealand Community Fault Model (NZ CFM; Seebeck et al., 2022, 2024), beach ball plots for events in the GeoNet regional moment tensor (RMT) catalog (2004–2025; Ristau, 2013), and the azimuth of the maximum horizontal stress (azS_{Hmax}) from borehole breakouts (as compiled in the World Stress Map; Heidbach et al., 2018). Inset, motion (DeMets et al., 2010) and principal structures between the Australian (AUS) and Pacific (PAC) plates in the South Island; AF, Alpine Fault; PSZ, Puysegur subduction zone. Italicized text; fault names. (b) Network configurations and seismicity recorded by the OtagoNet (March 2014–April 2015; Reyners et al., 2017) and Southland Otago Seismic Array (SOSA, October 2022–October 2023; Williams et al., 2025b).

3.2 Focal mechanism determination

Focal mechanisms are derived from the OtagoNet and SOSA deployments for earthquakes that had ≥ 8 manually picked P -wave polarities ($npol$) on the vertical channel. A quality (0, 1, or 2) was assigned to the polarity based on the pick quality. Events with focal depths > 40 km were excluded as these earthquakes are likely to be nucleating within subducted remnants of the Hikurangi Plateau (Reyners et al., 2011, 2017; Eberhart-Phillips et al., 2018). As such, the stresses these deep earthquakes are responding to are not necessarily mechanically coupled to this region's ~ 15 km (in Canterbury and Otago) to ~ 40 km (in Southland) thick seismogenic layer (Warren-Smith et al., 2017a; Eberhart-Phillips et al., 2022b; Williams et al., 2025b).

We constrained focal mechanisms from these events based on their P -wave polarities and S -wave/ P -wave (S/P) amplitude ratios using the program HASH v1.2 (for Hardebeck & Shearer; Hardebeck and Shearer, 2002). A full description of HASH is provided in Hardebeck and Shearer (2002) and Hardebeck (2003), and the settings we use are included in Table 1. However, in summary, for a given event, HASH first performs a grid search to identify an 'acceptable' set of focal mecha-

nisms where the weighted proportion of misfit P -wave polarities ($mfrac$) and S/P ratios are less than a given threshold. Here, we set the $mfrac$ threshold so that it is the greater of: (1) the number of misfit polarities for the best-fit mechanism ($npol_{\phi}$) plus an additional *nextra* misfits, or (2) $ntotal$, which is defined as $npol$ multiplied by the fraction of assumed bad polarities (*badfrac*, set here to 10%, Table 1). We adopt the default HASH settings so that *nextra* is half of $ntotal$.

The S/P ratio can also be used to filter mechanisms as P -wave amplitudes increase at stations that plot close to the mechanism's P and T axes on a source's focal sphere, whereas S -wave amplitudes are largest for stations that plot near the nodal planes (Hardebeck, 2003; Yang et al., 2012). Notably, S/P ratios can increase the number of observations for constraining the focal mechanism, as they can use information from stations where there are travel-time picks but no polarity picks. Following Hardebeck (2003) and Yang et al. (2012), we measured P and S amplitudes from the vector norm of the maximum amplitudes on each of the three-component's waveforms after correcting for instrument response and filtering between 2–15 Hz. The minimum allowed P - and S -to-noise amplitude ratio, *ratmin*, is set

to 1 and 3 respectively (Table 1). A mechanism is accepted if the sum misfit between the mechanism's theoretical $\log(S/P)$ ratio and the observed $\log(S/P)$ ratio at each station ($qmis$) is less than a given threshold, which similar to polarity misfit threshold, is given by the greater of: (1) the sum of best-fit mechanism's $qmis$ ($qmis_\phi$) and $qextra$ or (2) $qtotal$ (Table 1). In turn, $qtotal$ is the assumed noise in the amplitude ratios ($qbadfrac$) multiplied by the number of (S/P) observations, and $qextra$ is the larger of $qmisup$ or half of $qtotal$ (Table 1).

The process for finding acceptable mechanisms is then repeated in HASH using randomly changed 3-D raypaths for each event. The degree of these raypath perturbations are based on their azimuth and take-off angle error, which are calculated in Simul2023 from the event's hypocenter uncertainty. From the perturbed ray paths, additional acceptable mechanisms may be found. We perform this analysis following 30 trials, and where in each trial, the grid search for acceptable mechanisms is performed using a 5° grid spacing ($dang$, Table 1). If <10 accepted mechanisms are found, an additional search for solutions is made using $1.5 \times qmisup$.

To select a 'preferred' mechanism we find the five accepted mechanisms with the smallest $mfrac$, and from these, select the mechanism that has the smallest angular distance to the average P- and T-axis of all accepted mechanisms. In this way, our preferred solution balances the need to minimize solution misfits, and to ensure that it is not an outlier with respect to the accepted mechanisms. A quality A-D is also assigned to each focal mechanism based on: $mfrac$, the total number of polarity and S/P observations ($nobs$), the azimuthal gap (gap), the root-mean-square angular difference between the acceptable mechanism's P- and T-axes and the preferred mechanism's axes (fm_rms), and the proportion of acceptable mechanisms whose P- and T-axes are $<30^\circ$ from the preferred mechanism (fm_prop , Table 2, Fig. 2).

3.3 Stress inversion

Using the 91 A-C quality focal mechanisms derived from the OtagoNet and SOSA data, we conduct a stress inversion for the southeastern South Island using the program STRESSINVERSE (Vavryčuk, 2014). In addition, we incorporate 11 focal mechanisms reported by Warren-Smith et al. (2017a) that coincide with the north and western parts of our study area (Fig. 3), and that were obtained using the Central Otago Seismic Array (COSA) network between 2012-2013.

STRESSINVERSE solves for the orientations and relative magnitudes of the three principal stress by using a linear stress inversion method that recognizes that:

$$At = s \quad (1)$$

where A is a 3×5 matrix calculated from the fault normal, s is the slip vector on the fault, and t is the vector of stress components (Michael, 1984). Hence, for a set of m mechanisms, it is possible to extend Eq. 1 into $3 \times m$ linear equations, and in which t can be solved using a linear least squares technique. Implicit in this approach is that: (1) the stress tensor is uniform within the

region in which the focal mechanisms occur, (2) the slip vector is parallel to the direction of maximum resolved shear stress on the fault (i.e., the 'Wallace-Bott hypothesis'; Wallace, 1951; Bott, 1959), and (3) the trace of the stress tensor is zero (Michael, 1984).

A limitation of focal mechanism stress inversions is that the two nodal planes do not necessarily represent conjugate fault planes (Twiss and Unruh, 1998). Without prior knowledge of the earthquake's fault plane, it is therefore possible that the resulting stress tensor is influenced by the inversion incorrectly using the focal mechanism's auxiliary plane (Michael, 1987; Lund and Slunga, 1999; Martínez-Garzón et al., 2016). To address this, STRESSINVERSE first performs $N_realizations$ iterations of the Michael (1984) stress inversion using randomly selected nodal planes. Then using the vector norm of these $N_realizations$ stress tensors, the Mohr-Coulomb criterion is used to identify the nodal plane from each event that is most susceptible to failure (I), and this is selected as the fault plane during subsequent iterations (Vavryčuk, 2014). Here, I represents the ratio between the effective normal and shear stresses acting on a nodal plane relative to those on a fault that is optimally oriented in that stress state (Vavryčuk, 2014). To calculate I , we considered a range of fault's frictional strength estimates, μ , between 0.4-1.0 and at intervals of 0.05, and select the μ that results in the highest mean value of the focal mechanism's instability (I_{mean}). This nodal plane selection procedure is then repeated another $N_iterations$ times using the optimum value for μ .

STRESSINVERSE considers focal mechanism uncertainty by adding noise, with an assumed mean deviation, to each mechanism's nodal plane orientations and rake. The stress inversion procedure is then repeated $N_noise_realizations$ times using the randomly perturbed nodal planes (Vavryčuk, 2014). Here, we instead randomly select $N_noise_realizations$ 'acceptable' mechanism that HASH returned for each event, and use these solutions to perform the stress inversions. We maintain the default values in STRESSINVERSE for $N_realizations$ (10), $N_iterations$ (6) and $N_noise_realizations$ (100).

In addition, we weight focal mechanisms in STRESSINVERSE by the quality assigned to them using Table 2: $w = 3$ for A-quality, $w = 2$ for B quality, and $w = 1$ for C-quality. Kilb and Hardebeck (2006) recommend that only focal mechanisms with $fm_rms < 35^\circ$ are used in stress inversions, and although our criteria for C-quality focal mechanisms is $fm_rms < 45^\circ$ (Table 2), only 14 of the 91 OtagoNet and SOSA C or better quality focal mechanisms had $fm_rms > 30^\circ$ and none had $fm_rms > 35^\circ$. We assign a nominal uncertainty of 15° to the strike, dip, and rake of the COSA focal mechanisms, and since they were derived using between 8-13 polarity observations (Warren-Smith et al., 2017a), they are assigned as C quality focal mechanisms.

To test if the stress state is uniform in the southeastern South Island, we subdivide the focal mechanisms using two approaches. In the first instance, focal mechanisms are grouped into three sub-regions based on NZ CFM fault orientations and crustal rheology (Fig. 3): (1) Southland, where there is a mixture of NE- and NW-

	Setting	Description	Value
Event selection	<i>npol</i>	Number of polarity observations	
	<i>nspr</i>	Number of <i>S/P</i> ratio observations	
	<i>nobsmin</i>	Minimum of <i>npol</i> + <i>nspr</i>	9
	<i>delmax</i>	Maximum allowed epicentral distance (km)	300
	<i>mvpqual</i>	maximum <i>P</i> -pick quality	2
Polarity misfits	<i>mfrac</i>	Weighted fraction misfit polarities	
	<i>badfrac</i>	Fraction of polarities assumed bad	0.1
	<i>npol_φ</i>	Number of misfit polarities for best fitting mechanism	
	<i>ntotal</i>	Parameter for <i>mfrac</i> threshold	$npol * badfrac$
	<i>nextra</i>	Parameter for <i>mfrac</i> threshold	$ntotal * 0.5$
	<i>mfrac</i> threshold	Acceptable number of polarity errors	$max(npol_{\phi} + nextra, ntotal)$
	<i>ratmin</i>	Minimum allowed <i>P</i> -signal to noise ratio	1.0
Log <i>S/P</i> ratios	<i>ratmin</i>	Minimum allowed <i>S</i> -signal to noise ratio	3.0
	<i>qmis</i>	Sum misfit between mechanism's theoretical and observed log(<i>S/P</i> ratio)	
	<i>qbadfrac</i>	Assumed noise in <i>S/P</i> amplitude ratios in log10 scale	0.15
	<i>qmis_φ</i>	<i>qmis</i> of best fit mechanism	
	<i>qmisup</i>	Limit for acceptable <i>S/P</i> amplitude ratio misfit	3
	<i>qtotal</i>	Parameter for <i>qmis</i> threshold	$nspr * qbadfrac$
	<i>qextra</i>	Parameter for <i>qmis</i> threshold	$max(qtotal * 0.5, qmisup)$
	<i>qmis</i> threshold	Acceptable log10(<i>S/P</i>) misfit	$max(qmis_{\phi} + qextra, qtotal)$
	<i>dang</i>	Grid search angle focal mech (°)	5
Grid Search	<i>nmc</i>	Number of trials	30
	<i>maxout</i>	Maximum returned focal mechanisms	500
	<i>prob_max</i>	Probability threshold for multiples	0.2

Table 1 Explanation and values of settings applied in HASH

Quality	<i>nobs</i>	<i>gap</i>	<i>mfrac</i>	<i>fm_prop</i>	<i>fm_rms</i>	<i>n</i> OtagoNet Events	<i>n</i> SOSA Events
A	≥40	≤140°	≤10%	≥90%	≤25°	3	3
B	≥25	≤210°	≤20%	≥60%	≤35°	15	19
C	≥10	≤270°	≤30%	≥50%	≤45°	44	7
D			all other events			34	1

Table 2 Criteria used to determine focal mechanism quality: *nobs*, number of polarity and *S/P* ratio observation; *gap*, azimuthal gap; *mfrac*, weighted fraction of misfit polarities; *fm_prop*, proportion of acceptable mechanisms with an angular distance <30° from the preferred mechanism; *fm_rms*, root-mean-square of the angular distance between the preferred and acceptable mechanisms. We also report the number of events for each quality level for the OtagoNet and SOSA data.

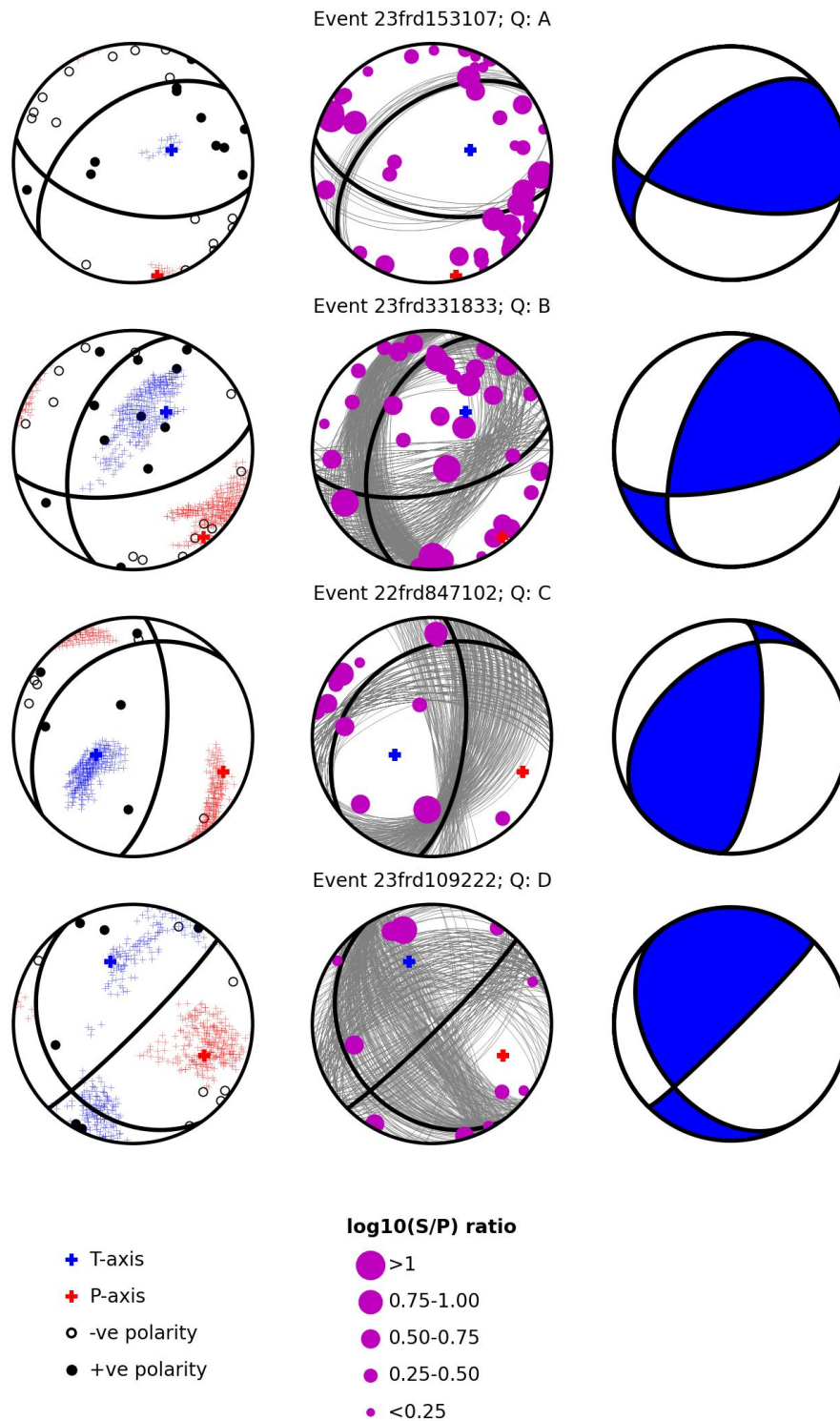


Figure 2 Examples of *A* to *D* quality focal mechanisms resolved from SOSA. For each event, the left plot indicates: the recording station's projection and first motion polarity, the preferred and accepted *P*- and *T*-axes, and the preferred nodal planes. In the center column, we show the *S/P* ratio at each recording station and the range of accepted nodal planes. Right column shows the event's preferred focal mechanism as a beach ball plot.

striking reverse faults, and the crust is composed of relatively strong and rigid mafic terranes that were accreted onto the Gondwana margin during the Mesozoic (Turnbull and Allibone, 2003; Eberhart-Phillips et al., 2022b; Williams et al., 2025b), (2) the Otago 'Range and Basin Province,' which is dominated by NE-striking reverse faults hosted in relatively weak quartzofelspathic

Haast Schist (Turnbull, 2000; Norris, 2014; Eberhart-Phillips et al., 2018, 2022b), and (3) the Waitaki region, which lies at the transition between Haast Schist and relatively strong Rakaia Terrane derived greywacke, and is dominated by the NW-striking Waitaki and Waihemo reverse fault systems (Forsyth, 2002; Upton et al., 2009; Barrell, 2016).

In our second approach, we objectively group the focal mechanisms using a k -means algorithm (Hartigan and Wong, 1979; Martínez-Garzón et al., 2016; Warren-Smith et al., 2017b). This algorithm assigns earthquakes to clusters through an iterative approach that minimizes an error function between the earthquake locations and a predefined number of clusters. Given the 102 available focal mechanisms, and that the number of events in each cluster should be ≥ 30 (Martínez-Garzón et al., 2016), we tested groupings with two or three clusters. We then selected the grouping that returns the highest average silhouette coefficient (Rousseeuw, 1987; Martínez-Garzón et al., 2016), which in this instance, is the one with two clusters (scores are 0.55 and 0.51 for the groupings with two and three clusters respectively, Fig. S1).

We also conducted a stress inversion using the 25 solutions that are currently available for the southeastern South Island in the GeoNet Regional Moment Tensor (RMT) catalog (Fig. 1a; Ristau, 2013). These events occurred between 2004–2023 and had magnitudes M_W 3.5–4.7 (Fig. S2). To explore the RMT's uncertainty, we repeat these inversions $N_{noise_realizations}$ times using fault planes that are randomly sampled from uniform distributions that are centered on the RMT solution's fault plane and bounded by nominal uncertainties of $\pm 5^\circ$, $\pm 10^\circ$, and $\pm 15^\circ$ for strike, dip, and rake respectively.

4 Results

4.1 Focal mechanisms

In total, we extract 96 and 30 focal mechanisms from M_{LV} 1.14–4.3 events recorded by the OtagoNet and SOSA deployments respectively (see Williams et al., 2025a, for a full list). Focal mechanism qualities are typically B or C (Table 2). Overall, we resolve higher quality focal mechanisms from the SOSA data, which reflects that more polarity observations and S/P ratios were available for these events (average $nobs$ is 22 and 89 for events from the OtagoNet and SOSA data respectively).

The focal mechanisms we resolve are predominantly strike-slip ($n=74$), with 35 and 17 reverse and normal focal mechanisms respectively. For comparison, if we only consider the 91 A – C quality solutions, the number of strike-slip, reverse, and normal focal mechanisms are 57, 26, and 8 respectively. It is ambiguous whether a strike-slip focal mechanism alone indicates dextral or sinistral faulting. However, following the nodal plane selection routine in STRESSINVERSE (Section 3.3), we infer that these strike-slip focal mechanisms can be distinguished into a set of subvertical E -striking dextral and SE -striking sinistral faults (Figs. 3 and S3). The angle between the average inferred dextral and sinistral plane is 54° , which is consistent with them representing a set of conjugate faults with Byerlee friction (Scholz and Choi, 2022). Relatively few focal mechanisms are resolved in southern Otago, which reflects that the seismic arrays recorded few events in this region (Fig. 1b).

4.2 Stress inversion results

Stress inversions that consider all available focal mechanisms in the southeastern South Island indicate a strike-slip stress state with a WNW-trending sub-horizontal σ_1 (Table 3 and Fig. 4a). Once grouped by seismotectonic region, we find that the focal mechanisms in the Waitaki and Southland regions also indicate a strike-slip stress state with a WNW-trending σ_1 (Table 3 and Fig. 4b&d).

A reverse fault stress state is obtained from the Otago Range and Basin focal mechanisms (σ_v is equivalent to the minimum principal stress, σ_3); however: (1) the WNW trending σ_1 is the same as other regions, and (2) 43 out of the 100 $N_{noise_realizations}$ inversions favor a strike-slip stress state (i.e., σ_2 plunge $> \sigma_3$ plunge, Fig. 4c). Indeed, 16/26 focal mechanisms in this region are strike-slip. We therefore suggest that it is equivocal from these stress inversions whether this region is under a reverse or strike-slip stress regime.

By alternatively grouping the focal mechanisms using a k -means clustering algorithm, we find similar stress states to the complete focal mechanism dataset (Table 3 and Fig. S4). The principal stress orientations for Cluster 2 are similar to those indicated for the Southland region (compare Figs. S4b and 4c). This reflects that Clusters 1 and 2 are divided by the region in southern Otago with relatively few focal mechanisms, and so the latter's spatial extent is similar to the Southland region (compare Figs. 3 and S1).

A reverse fault stress state with a gently plunging WNW trending σ_1 is obtained from the southeastern South Island's RMT solutions (Fig. 4e and Table 3). However, there is high uncertainty in the plunge of σ_2 and σ_3 . In all inversions, the stress shape ratio ($R = \sigma_1 - \sigma_2 / \sigma_1 - \sigma_3$) is ≥ 0.72 (Table 3, Figs. S5 and S6).

To examine the influence of STRESSINVERSE's procedure of using instability, I , to iteratively select nodal planes, we compare the stress tensor derived in the final iteration with that obtained by randomly selecting nodal planes. The average instability of focal mechanisms, I_{mean} , in these two inversions are 0.93 and 0.73 (Table 'ref_instability_info' in at Williams et al. (2025a)). Our comparison indicates that there is little difference in the principal stress orientations obtained from these two inversions (Table 3). However, R is significantly higher in the final iteration's stress tensor (0.74 vs 0.94). Hence, using I to iteratively selecting nodal planes in stress inversions primarily influences the stress shape ratio only (Michael, 1987; Vavryčuk, 2014; Martínez-Garzón et al., 2016).

5 Discussion

5.1 The stress state within the southeastern South Island

From considering all available focal mechanisms derived from the OtagoNet, SOSA, and COSA deployments, we infer a strike-slip stress state in the southeastern South Island with a WNW trending σ_1 and stress shape ratio, R , slightly less than 1 (Fig. 4a, Table 3). Spatially subdividing the focal mechanisms does indicate

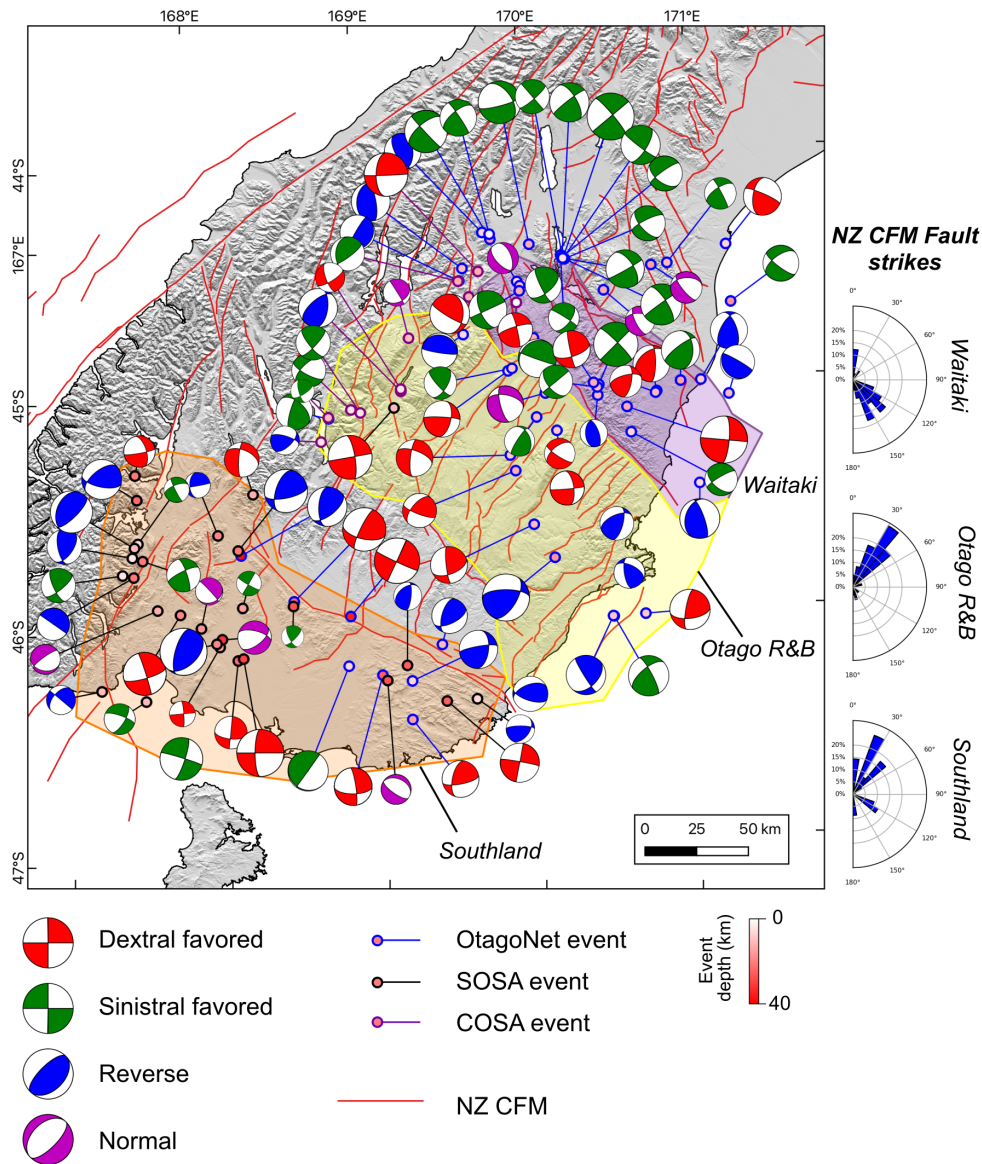


Figure 3 Beach ball plots showing the preferred first motion focal mechanisms derived from the OtagoNet and SOSA data. *D* quality events are excluded. We also show the 11 focal mechanisms constrained using the COSA (Warren-Smith et al., 2017a) that coincide with our study area east of the Southern Alps, and that are incorporated in our stress inversion. For strike-slip focal mechanisms, the beach balls are colored based on the kinematics of the nodal plane favored by STRESSINVERSE. Beach ball plot size scaled by event magnitude. Shading indicates the extent of regions from which focal mechanisms are selected for the Southland, Otago Range and Basin (R&B) and Waitaki stress inversions (Section 3.3). Side bar shows length-weighted rose plots for NZ CFM fault strikes in each of these regions.

that some small variations in the stress state may exist: an 8° clockwise rotation in the trend of σ_1 between the Otago Range & Basin province and Southland/Cluster 2 (Table 3), and a switch to reverse fault stress state in the Otago Range & Basin province. However, in the latter case, it is within our uncertainty that the stress state is strike-slip. More broadly, we highlight that in order for stress inversions to retrieve the correct stress orientations, the observed and theoretical fault slip vector orientations and symmetries should match (Twiss and Unruh, 1998). However, this assumption can break down, particularly in cases when there are limited data ($n < 50$) and R is close to 1 (Martínez-Garzón et al., 2016). Hence, although we cannot exclude that the local varia-

tions in stress in Southland and Otago are real, our preferred interpretation is that the focal mechanisms indicate a broadly uniform stress state across the southeastern South Island.

If true, it indicates for the first time that this region's ESE trending maximum horizontal stress azimuth (azS_{HMax}) and strike-slip stress state is the same as inferred for elsewhere on the South Island (azS_{HMax} $115 \pm 10^\circ$; Balfour et al., 2005; Townend et al., 2012; Sibson et al., 2012; Holt et al., 2013; Warren-Smith et al., 2017b; Matsuno et al., 2022). To the first order, this includes on the plate-bounding Alpine Fault itself (azS_{HMax} between 107 – 121° ; Leitner et al., 2001; Boese et al., 2012; Michailos et al., 2020; Warren-Smith et al., 2022). Our

Data	Events	Stress State	σ_1 (plunge/ trend)	σ_2 (plunge/ trend)	σ_3 (plunge/ trend)	Stress Shape Ratio (R)	azS_{HMax}
All	102	strike-slip	01/296 (3)	77/204 (8)	13/026 (7)	0.94 (0.03)	116 (2)
All ref	102	strike-slip	01/116	77/209	13/026	0.74	116
Southland	36	strike-slip	06/124 (7)	63/225 (9)	27/031 (7)	0.76 (0.06)	124 (3)
Otago R&B	26	reverse	03/296 (8)	19/027 (43)	71/198 (43)	0.72 (0.1)	116 (5)
Waitaki	24	strike-slip	05/291 (8)	84/149 (11)	03/022 (7)	0.78 (0.07)	111 (3)
Cluster 1	62	strike-slip	03/110 (5)	87/321 (10)	02/200 (8)	0.82 (0.05)	110 (2)
Cluster 2	40	strike-slip	03/124 (7)	55/219 (9)	35/032 (7)	0.77 (0.07)	124 (3)
GeoNet RMT catalog	25	reverse	01/301 (4)	23/032 (21)	67/208 (20)	0.89 (0.06)	121 (3)

Table 3 Principal stress orientations, stress shape ratio (R), and azimuth of the maximum horizontal compressive stress (azS_{HMax}) obtained for the southeastern South Island from STRESSINVERSE. Numbers in brackets indicate uncertainties. For the principal stress orientations, uncertainties are represented by the average angular distance between the preferred stress orientations and those returned from the 100 $N_{noise_realizations}$ inversions (see Section 3.3). The uncertainties of R and azS_{HMax} indicate one standard deviation of the $N_{noise_realizations}$ inversions. Polygons used to divide focal mechanisms between the Southland, Otago Range and Basin(R&B), and, Waitaki regions are shown in Fig. 3. ‘All ref’ refers to the stress tensor returned from a stress inversion that incorporates randomly selected nodal planes.

interpretation also indicates that variations in NZ CFM fault orientations between Southland, the Otago Range and Basin province and the Waitaki (Fig. 3), nor differences in the rheology of basement terranes, correspond to regional azS_{HMax} rotations.

5.2 Controls on fault orientation and reactivation in the southeastern South Island

Collectively, the first motion focal mechanisms, regional moment tensors, and NZ CFM indicate that active reverse and strike-slip faults are present in the southeastern South Island of New Zealand. Elsewhere on the South Island, [Sibson et al. \(2012\)](#) used the example of the Canterbury Earthquake Sequence to propose that the coexistence of these fault types was facilitated by a R close to 1, as this implies that σ_2 and σ_3 can readily switch. Our stress inversions indicate that $R > 0.72$ (Table 3, Fig. S5), and so this explanation can, at least partially, account for reverse and strike-slip faulting in the southeastern South Island too.

We highlight, however, that the first motion focal mechanisms typically indicate slip on E-W dextral or SE-NW sinistral fault planes (Figs. 5, 6, and S3), which given their M_{Lv} 1.14–4.3 magnitudes, correspond to events with a rupture diameter (r) ~ 0.04 –0.5 km (assuming that the scaling between r and seismic moment, $M_0 = \frac{2}{7}\Delta\sigma r^3$, where $\Delta\sigma$ is stress drop (2.5 MPa) and that $\log_{10} M_0 = 1.0M_L + 9.8$; [Abercrombie, 1995, 1996](#); [Scholz, 2019](#)). Conversely, the NZ CFM, in conjunction with this region’s paleoseismic record (e.g., [Barrell, 2016, 2019](#); [Williams et al., 2025c](#)), indicates that surface rupturing ($M_W \geq 7.0$, $r \geq 20$ km) earthquakes in the southeastern South Island release strain on NE-, and subordinate NW-, striking reverse faults (Figs. 1a, 5d and 6b). This coexistence of relatively small-scale strike-slip and large-scale reverse faults in the southeastern South Island cannot be readily explained by a high R alone. Furthermore, a high R cannot account for the presence of active NE- and NW-striking reverse faults in this region, as this requires that σ_1 and σ_2 are similar in magnitude ([Upton et al., 2009](#)).

We therefore propose that the southeastern South Island focal mechanisms predominantly record slip on small-scale ($r < \sim 0.5$ km diameter) strike-slip faults in ‘background’ crust (Fig. 7a), and which in the context of Andersonian fault mechanics, are favorably-oriented for reactivation in this region’s stress state ($I_{mean} = 0.93$, although we acknowledge there is some circularity here, as STRESSINVERSE will select the nodal plane that is more susceptible to failure). By contrast, we infer that the NZ CFM NE- and NW-striking reverse faults are currently active due to local stress state rotations within the damage zones of non-optimally oriented (I_{mean} for the southeastern South Island’s NZ CFM faults = 0.80) Permian-Jurassic reverse faults and Cretaceous to mid-Cenozoic normal faults and shear zones in the southeastern South Island (Fig. 7a; e.g., [Norris et al., 1990](#); [Turnbull et al., 1993](#); [Landis et al., 1999](#); [Turnbull, 2000](#); [Litchfield, 2001](#); [Turnbull and Allibone, 2003](#); [Norris, 2014](#); [Mortimer et al., 2023](#)).

In detail, two types of changes to the strike-slip stress state suggested by the focal mechanisms are required to explain the activation of non-optimally oriented reverse faults in the southeastern South Island. Firstly, σ_2 and σ_3 must locally rotate about a vertical plane orthogonal to σ_1 so that they switch positions, and NE-striking faults can activate as reverse faults ([Koons, 1994](#); [Enlow and Koons, 1998](#)); the possibility of which is favored by the prolate stress ellipsoids we infer for this region (i.e., R is close to 1 and the magnitude of $\sigma_2 \sim \sigma_3$, Table 3). In addition, the activation of the NW striking Waitaki faults requires that σ_1 and σ_2 locally rotate about a horizontal axis ([Upton et al., 2009](#)). In both cases, these rotations can be driven by small changes in the horizontal or vertical shear stress ([Enlow and Koons, 1998](#); [Upton et al., 2009](#)) that could conceivably occur in the relatively fractured and compliant damage zones of these faults ([Twiss and Unruh, 1998](#); [Faulkner et al., 2006](#); [Gudmundsson et al., 2010](#); [Ziegler et al., 2024](#)).

Overall, a reverse fault stress state is obtained from 25 M_W 3.5–4.7 RMTs in the southeastern South Island (Fig. 4e and Table 3). However nearly half of the RMTs (11/25)

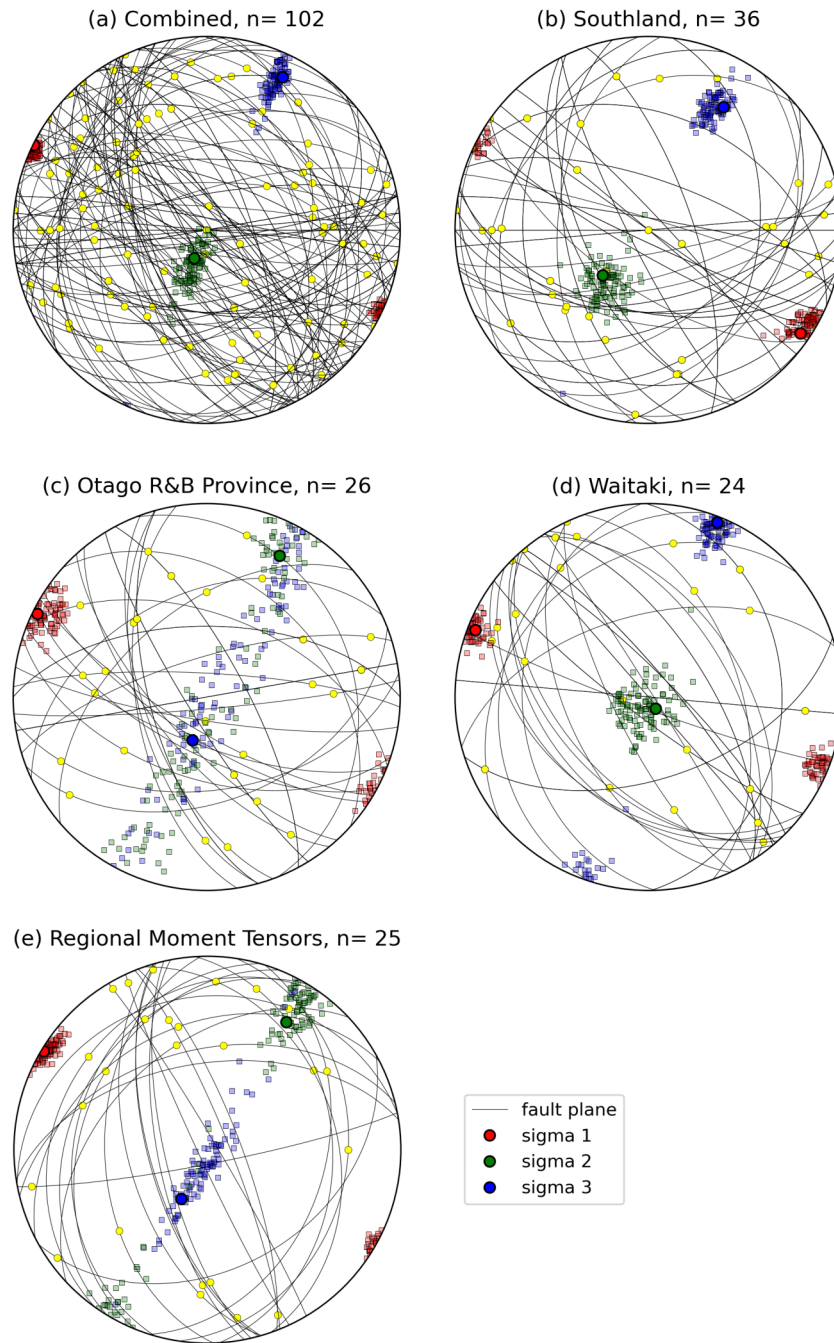


Figure 4 Lower hemisphere equal area stereonets depicting the orientations of the three principal stresses returned by STRESSINVERSE. Large red, green, and blue circle symbols represent the stress axes derived the ‘preferred’ focal mechanisms returned by HASH. Smaller colored squares represent the stress axes from 100 inversions that use randomly sampled ‘accepted’ focal mechanisms. The orientation and rake of each event’s preferred nodal planes, as selected by STRESSINVERSE, are plotted as great circles with yellow squares. Plots are arranged to indicate the principle stresses from considering: (a) all available first motion focal mechanisms in the southeastern South Island, (b)-(d) focal mechanisms grouped by regions shown in Fig. 3, and (e) from events in the GeoNet Regional Moment Tensor catalog (Fig. 1a.)

are strike-slip events. We therefore suggest that the M_W 3.5-4.7 RMT events ($r \sim 0.5$ -2.5 km) are within the transition between slip preferentially occurring on strike-slip faults in background crust or on non-optimally oriented reactivated reverse faults. We do not wish to explicitly assign a maximum magnitude to strike-slip earthquakes in the southeastern South Island. Nevertheless, we suggest that instead of assigning an equal weighting to re-

verse or strike-slip $4.95 \leq M_W \leq 8$ earthquakes for this region in the 2022 NZ NSHM distributed seismicity model (Thingbaijam et al., 2023), future updates should favor reverse fault earthquakes.

Our hypothesis of scale dependent fault kinematics cannot account for all of the southeastern South Island’s faults. For example, 35/126 of the focal mechanisms indicate reverse faulting (Fig. 3). Although it is possible

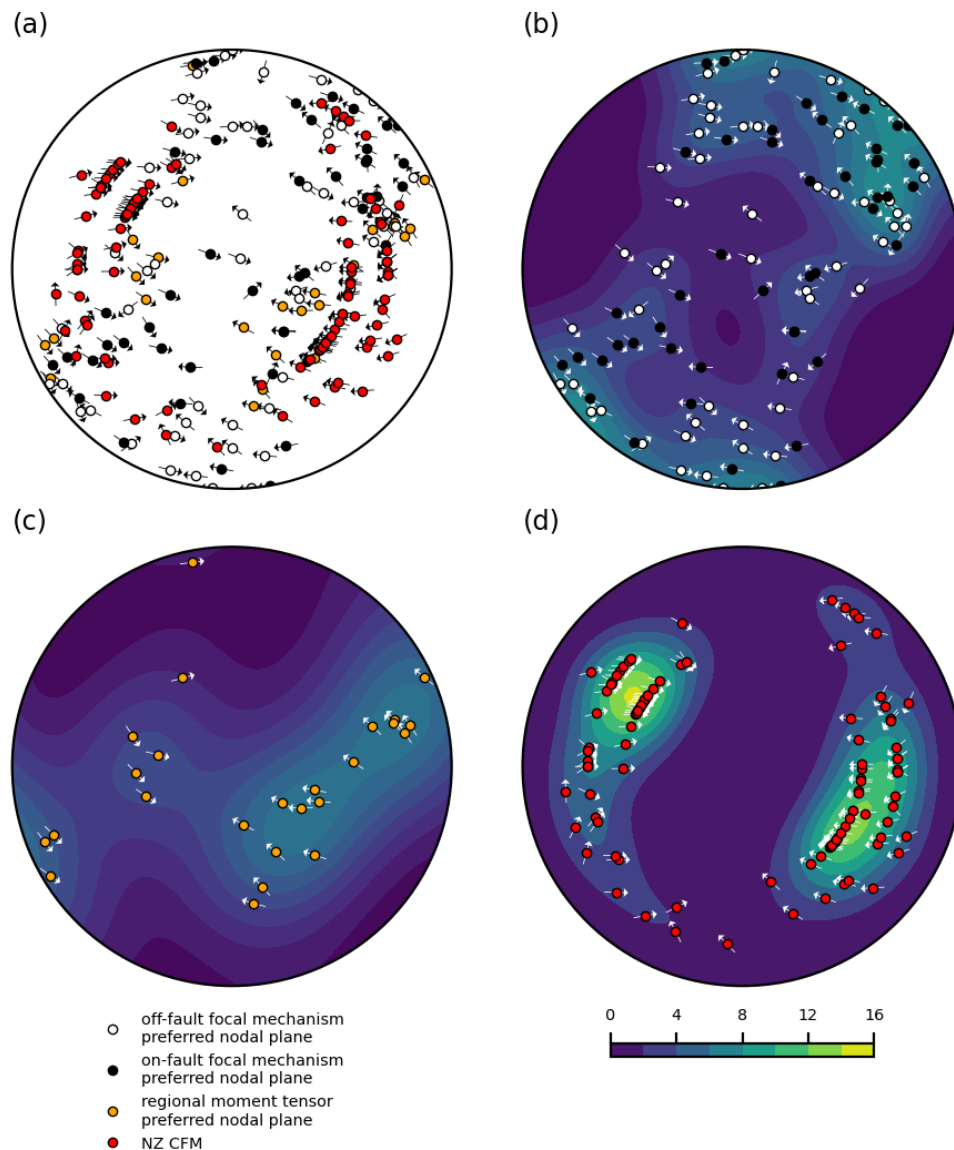


Figure 5 Tangent lineation plot for faults in the southeastern South Island from considering the first motion focal mechanism's (C quality or better), regional moment tensors, and the NZ CFM (Seebeck et al., 2024). Plots follow the convention of Twiss and Unruh (1998), so that fault orientations are represented as poles-to-planes, and the arrows indicate slip direction of material outside the plotting hemisphere (i.e., the footwall for inclined faults and lower hemisphere projection). The first motion focal mechanisms are colored based on whether they are located <3 km from the down-dip projection of a fault in the NZ CFM geometric model (Seebeck et al., 2022). In (b)–(d) we plot each data subset and contour poles using a modified version of the Kamb method (Vollmer, 1995).

that these focal mechanisms represent events within the damage zones of NZ CFM reverse faults, distinguishing between focal mechanisms that are located <3 and >3 km of a fault in the NZ CFM geometrical model does not result in any discernible differences in stress states (Fig. 8). Holocene sinistral motion has also been documented on the crustal-scale Fern Gully Fault (Barrell, 2016). Indeed, many NZ CFM faults in the southeastern South Island lack *in situ* constraints on their kinematics, and so the inference that they are reverse dip-slip faults is often based on expert judgment. We highlight, however, that aside from the Fern Gully Fault, active fault studies do indicate dip-slip reverse faulting in this region (e.g., Barrell, 2016, 2019; Taylor-Silva et al., 2020; Griffin et al., 2022; van den Berg et al., 2024; Williams et al., 2024; Meyer et al., 2025), and geodetic data indi-

cates that uniaxial compression is the predominant signature of elastic strain accumulation in the Otago Range and Basin province (Denys et al., 2016).

Instead of local stress rotations, an alternative explanation is that large-scale NE-striking reverse faults are activated in the southeastern South Island as they are frictionally weak (Smith et al., 2017), and under the Wallace-Bott hypothesis, would exhibit reverse fault slip in this region's strike-slip stress state anyway. While we do not entirely exclude this explanation, it would suggest that instead of activating as reverse faults, NW-striking faults in the Waitaki region should be predominantly sinistral. Indeed, our hypothesis for localized fault zone stress rotations is similar to numerical models that suggest these faults are activated due to a local switching between σ_1 and σ_2 at a rheologic transition

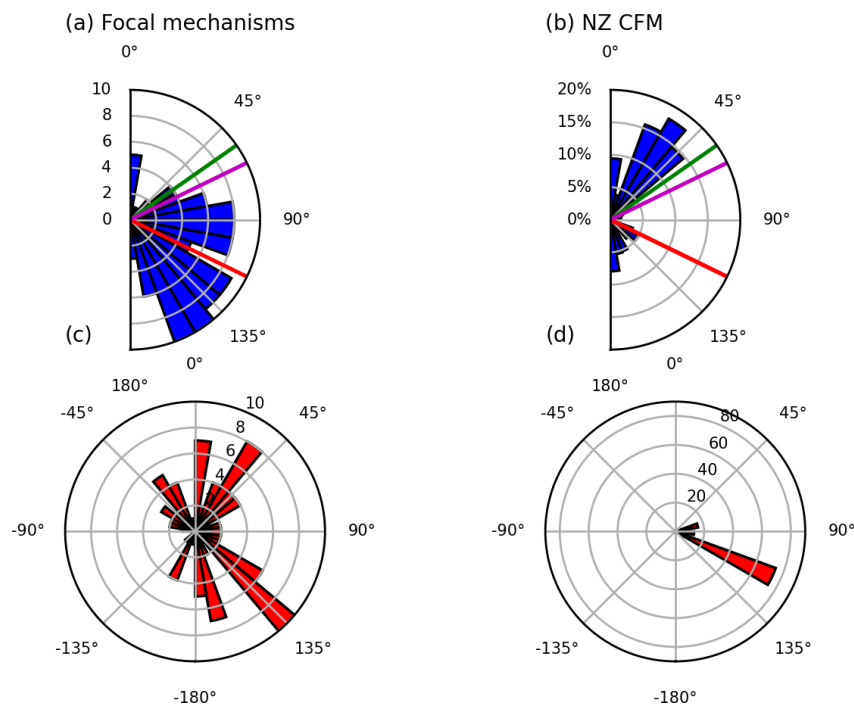


Figure 6 Rose plot indicating the distribution of fault strikes in the southeastern South Island from (a) the preferred nodal planes of OtagoNet, SOSA, and COSA first motion focal mechanisms (C quality or better) and (b) the NZ CFM. Strikes in (b) are weighted by fault length. Green, magenta, and red line indicates orientation of the plate motion margin (as indicated by the 055° striking Alpine Fault), plate motion vector (DeMets et al., 2010), and the 116° S_{Hmax} azimuth for the southeastern South Island (Table 3) respectively. (c&d) Equivalent to a&b but showing the distribution of rakes from (c) focal mechanisms and (d) NZ CFM faults.

between strong and weak lower crust in the Waitaki region (Upton et al., 2009, 2014). In detail, our stress inversions did not indicate a stress rotation within this region (Fig. 4d and Table 3); however, this does not preclude σ_1 and σ_2 switches occurring within individual fault zones due to a combination of pre-existing NW-striking faults (Forsyth, 2002; Gorman et al., 2013), and the reduced difference between the σ_1 and σ_2 at this region's rheologic transition (Upton et al., 2009).

5.3 Comparisons to slip partitioning in the South Island and beyond

Our observations of slip partitioning in the southeastern South Island are consistent with those from the central Southern Alps, where potentially active major faults indicate near pure-dip slip with an ESE shortening direction, while secondary faults and RMTs exhibit a combination of reverse and strike-slip faulting (Cox et al., 2012). In addition, the 1994 M_W 6.7 Arthur's Pass Earthquake is interpreted to have activated a NE-striking reverse fault within an overall strike-slip stress regime (Abercrombie et al., 2000; Robinson and McGinty, 2000). West of our study area, microseismicity is also dominated by strike-slip faulting (Warren-Smith et al., 2017a,b). However, slip is interpreted to preferentially occur on ENE-striking dextral planes, thereby indicating a rotation from E-striking dextral planes in our study area (Figs. 5) to ENE-striking as the Australian-Pacific plate boundary is approached.

To the north of our study area, it has been suggested that the E-striking dextral Greendale Fault, which ruptured during the M_W 7.1 2010 Darfield Earthquake, is reactivating a rheologic contrast where azS_{Hmax} is rotated $\sim 20^\circ$ anticlockwise to an E-W trend (Browne et al., 2012; Holt et al., 2013; Ellis et al., 2016). Hence, although the Greendale Fault has been previously suggested to be favorably oriented to the regional stress state (Sibson et al., 2012), it may actually be consistent with our suggestion of localized stress rotations occurring within southeastern South Island's pre-existing faults.

The slip partitioning we describe is also part of a larger system of how transpressive Australian-Pacific plate motion is accommodated in the southern South Island. Broadly speaking, the majority of the plate-parallel motion is localized on the southern section of the NE-striking dextral Alpine Fault, and the plate-normal component is accommodated on parallel offshore thrusts, the Puysegur subduction zone, and the Otago Range & Basin's and Southland's reverse faults (Fig. 7b; Norris and Cooper, 2001; Barth et al., 2014; Barnes, 2009; Seebeck et al., 2024). This partitioning of transpressional strain onto sub-parallel thrusts and strike-slip faults is also observed in other oblique subduction zones (e.g., Webb and Anderson, 1998; McCaffrey, 2009; Schütt and Whipp, 2020), California (e.g., Mount and Suppe, 1988; Lettis and Hanson, 1991; Miller, 1998) and elsewhere (Lanari et al., 2020; Waldien et al., 2023). However, the southeastern South Island indicates additional nuances for how transpressional strain

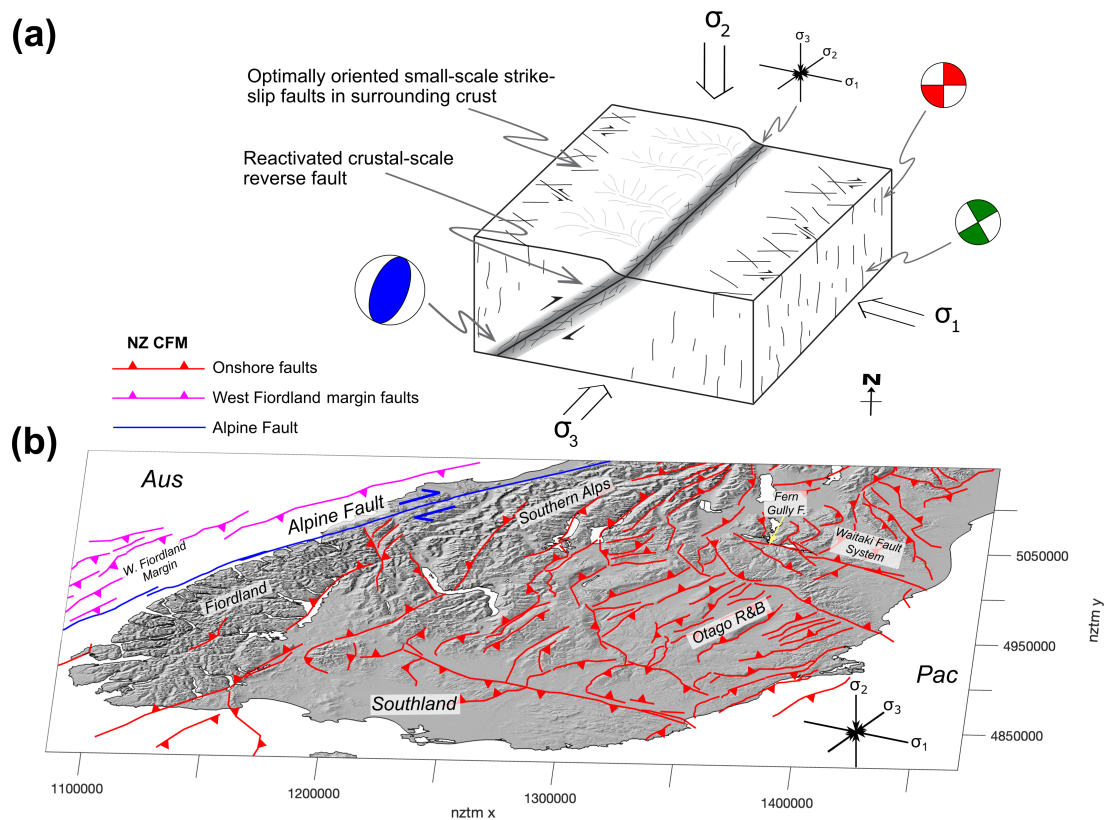


Figure 7 (a) Schematic representation of our model for scale dependent fault kinematics in the southeastern South Island. The first motion focal mechanisms predominantly sampled slip on small-scale (rupture radius 0.04–0.5 km) favorably oriented strike-slip faults. By contrast, the surface expressions of faulting in this region indicate slip on NE-striking reverse faults, and which we infer formed due to stress rotations within reactivated fault zones. (b) Oblique perspective of faulting across the Australian-Pacific plate boundary in the southern South Island, as indicated by the NZ CFM (Seebeck et al., 2024).

is partitioned in that: (1) slip partitioning is scale-dependent, (2) strike-slip faults are oblique to reverse faults and the plate boundary margin (Figs. 5 and 6), and (3) it highlights the role of stress rotations within pre-existing fault and shear zones during slip partitioning (Jones and Tanner, 1995; Waldien et al., 2023). Our observations of scale-dependent fault orientations bears similarities to those from Scholz and Choi (2022); however, instead of up-dip propagation of underlying viscous shear zones, we suggest that this scale dependence is driven by the reactivation of non-optimally oriented faults.

6 Conclusions

To examine how oblique motion between the Australian-Pacific plates is accommodated in the southeastern South Island of Aotearoa New Zealand, we used temporary seismic data to constrain focal mechanisms from 126 M_{Lv} 1.14–4.3 earthquakes. These focal mechanisms predominantly indicate slip on a conjugate set of E-striking dextral and NW-striking sinistral strike-slip fault planes with rupture diameters $< \sim 0.5$ km. A stress inversion conducted using these focal mechanisms also indicates a strike-slip stress state with an WNW-trending maximum principal compressive stress and stress shape ratio $< \sim 1$; a result

consistent with stress inversions conducted elsewhere on the South Island.

Unlike the strike-slip faulting indicated by the first motion focal mechanisms, the New Zealand Community Fault Model (NZ CFM, fault lengths > 10 km) implies that large magnitude surface rupturing events in the southeastern South Island activate NE, and subordinate NW, striking reverse faults. From these contrasting observations, we propose that the first motion focal mechanisms predominantly sample earthquakes on small-scale strike-slip faults that are favorably oriented for reactivation in this region's stress state. The larger-scale reverse faulting indicated by the NZ CFM reflects stress rotations and/or switches between the principal stress axes within reactivated faults and shear zones. If true, then the southeastern South Island highlights that pre-existing structures can lead to scale-dependent partitioning of transpressional strain on obliquely-oriented dip-slip and strike-slip faults.

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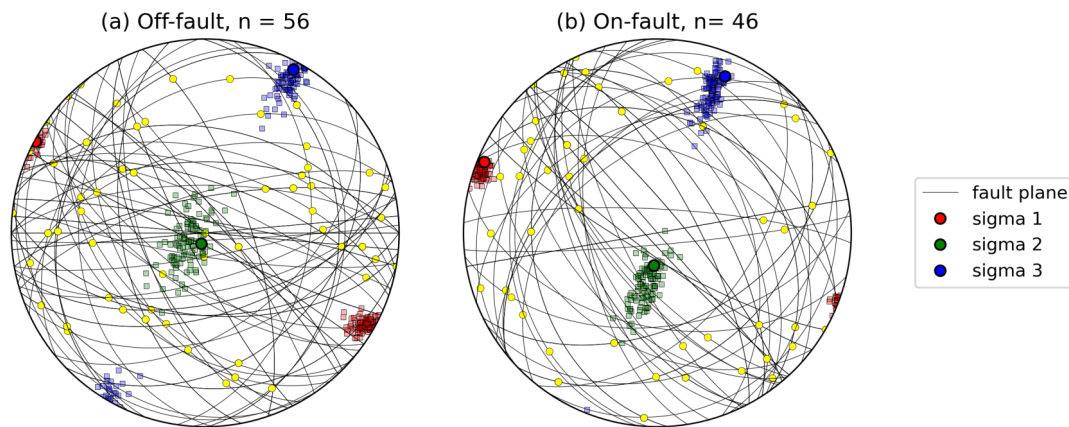


Figure 8 Orientation of the three principal compressive stresses for southeastern South Island focal mechanisms, once filtered for events that are located (a) >3 km or (b) <3 km from a fault in the NZ CFM (Seebeck et al., 2022). Figure follows convention of Fig 4, with smaller square symbols representing the stress axes from randomly sampled ‘accepted’ focal mechanisms, and the greater circles represent the orientation and rake of the preferred nodal plane selected by STRESSINVERSE. We highlight that this analysis does not consider uncertainty in the down-dip projection of NZ CFM faults, or that the stress rotations are occurring in zones <6 km wide (note that that a 1 km cut-off for ‘on-fault’ would result in only 12 ‘on-fault’ focal mechanisms in our catalog).

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Data and code availability

At Williams et al. (2025a), we have uploaded: supplementary figures S1-S6, a catalog for the 126 focal mechanisms resolved from the OtagoNet and SOSA deployments, focal mechanism plots for these events (following the template in Fig. 2), a catalog of the 11 focal mechanisms constrained from the COSA (Warren-Smith et al., 2017a) that are located within our study area, a RMT catalog for the southeastern South Island, and a list of the instability of the OtagoNet, SOSA, and COSA focal mechanisms in the stress tensors indicated by STRESSINVERSE (for events with quality greater than C).

Data from the OtagoNet and SOSA deployments are archived with the International Federation of Digital Seismograph Networks (FDSN) Web Service at Services at <https://doi.org/10.7914/jr68-qq17> (Reyners, 2014) and https://doi.org/10.7914/SN/6K_2014 (Williams et al., 2022) respectively. The GeoNet regional moment tensor catalog was obtained from: <https://github.com/GeoNet/data/tree/main/moment-tensor>

(date last accessed 28/02/2025) and the New Zealand Community Fault Model is available at: <https://www.gns.cri.nz/data-and-resources/new-zealand-community-fault-model/> (date last accessed 02/04/2025).

The HASH v1.2 program is available at: <https://www.usgs.gov/node/279393> (date last accessed 03/12/2024) and the STRESSINVERSE package (Vavryčuk, 2014) at: <https://www.ig.cas.cz/en/stress-inverse/> (date last accessed 13/01/2025). Stereonets depicting the accepted mechanisms P- and T-axes and beach ball plots of the preferred mechanism are plotted using mplstereonet (<https://mplstereonet.readthedocs.io/en/latest/index.html>, date last accessed 04/12/2024) and ObsPy (<https://docs.obspy.org>, date last accessed 04/12/2024) respectively.

Competing interests

The authors declare they have no competing interests.

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